

ER50-1900

ER50-1900,
Maxium payload 50 kg with maxium reach 1855 mm.

■ Highlights

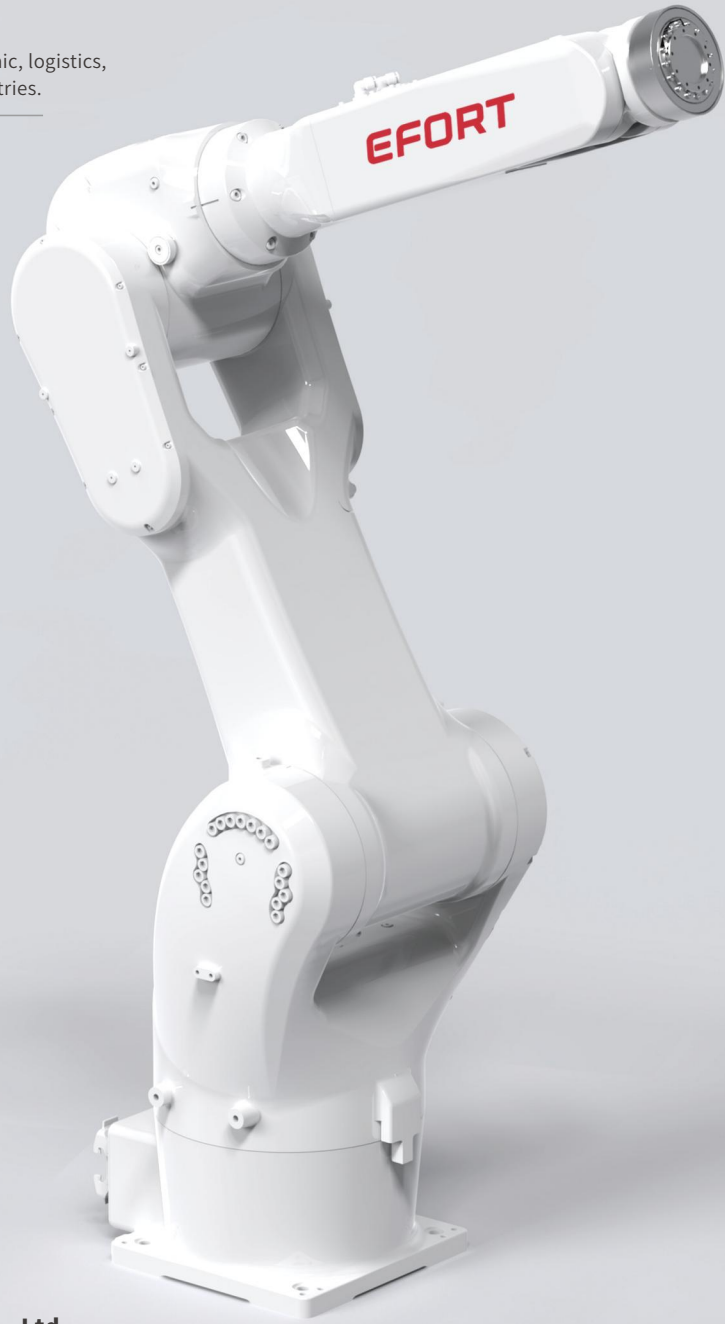
Thanks to the optimization of stiffness and inertia brought by the new mechanical design, with advanced trajectory algorithm. The takt improved by 20%-30%; Compact cabinet design helps customers deploy the production line with more flexibility.

■ Applications

It can be used in handling operations, assembling, grinding, polishing, deburring, etc.

■ Industries

Suitable for metal parts, photovoltaic, logistics, food and beverage and other industries.



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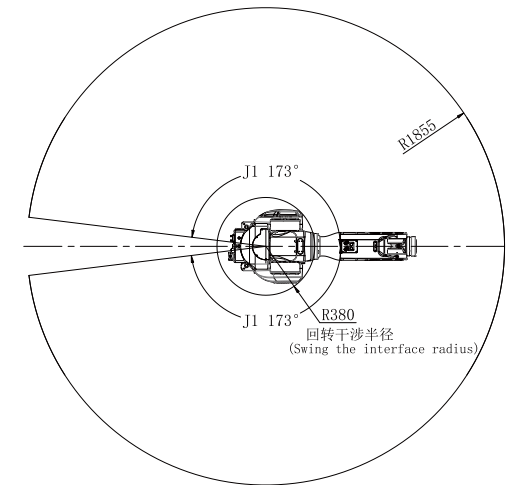
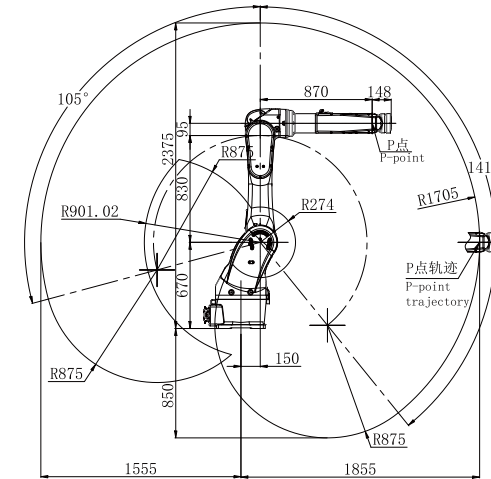
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SPECIFICATIONS

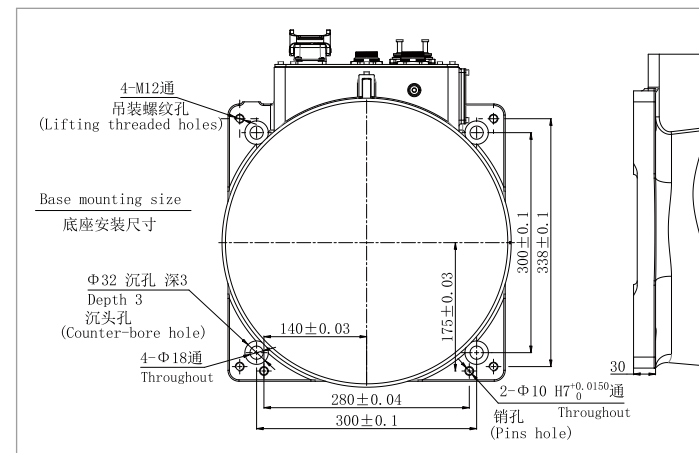
Model		ER50-1900
Type		Articulated
Controlled axes		6 Axes
Max. payload on wrist		50 kg
Repeatability		±0.05 mm
Robot weight		326 kg
Reach		1855 mm
Robot IP grade		IP54
Cabinet IP grade		IP20/ IP54 (Optional)
Drive mode		AC servo drive
Installation		Floor, Upside-down
Installation enviroment	Ambient temperature	0~45 °C
	Ambient humidity	RH≤80% (No dew nor frost allowed)
	Vibration acceleration	4.9 m/s ² (<0.5 G)

Allowable load moment at wrist	J4	185 N·m
	J5	185 N·m
	J6	120 N·m
Allowable load inertia at wrist	J4	13 kg·m ²
	J5	13 kg·m ²
	J6	10 kg·m ²
Maximum speed	J1	190°/sec
	J2	190°/sec
	J3	200°/sec
	J4	300°/sec
	J5	270°/sec
	J6	400°/sec
Motion range	J1	±173°
	J2	+105°/-141°
	J3	+200°/-78°
	J4	±190°
	J5	±120°
	J6	±360°

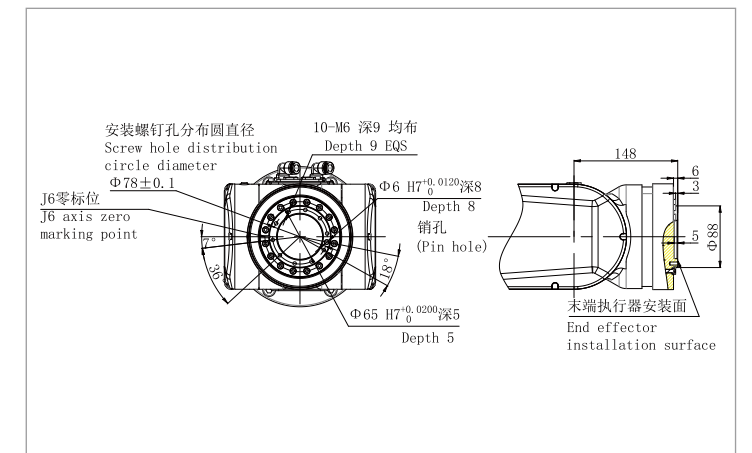
OPERATING SPACE



BASE MOUNTING SIZE



END FLANGE MOUNTING SIZE



*The final interpretation right belongs to EFORT Intelligent Robot Co., Ltd. Any updates will be made without prior notice.

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