

ER25-2300

ER25-2300,
Maximum payload 25 kg with maximum reach 2295 mm.

■ Highlights

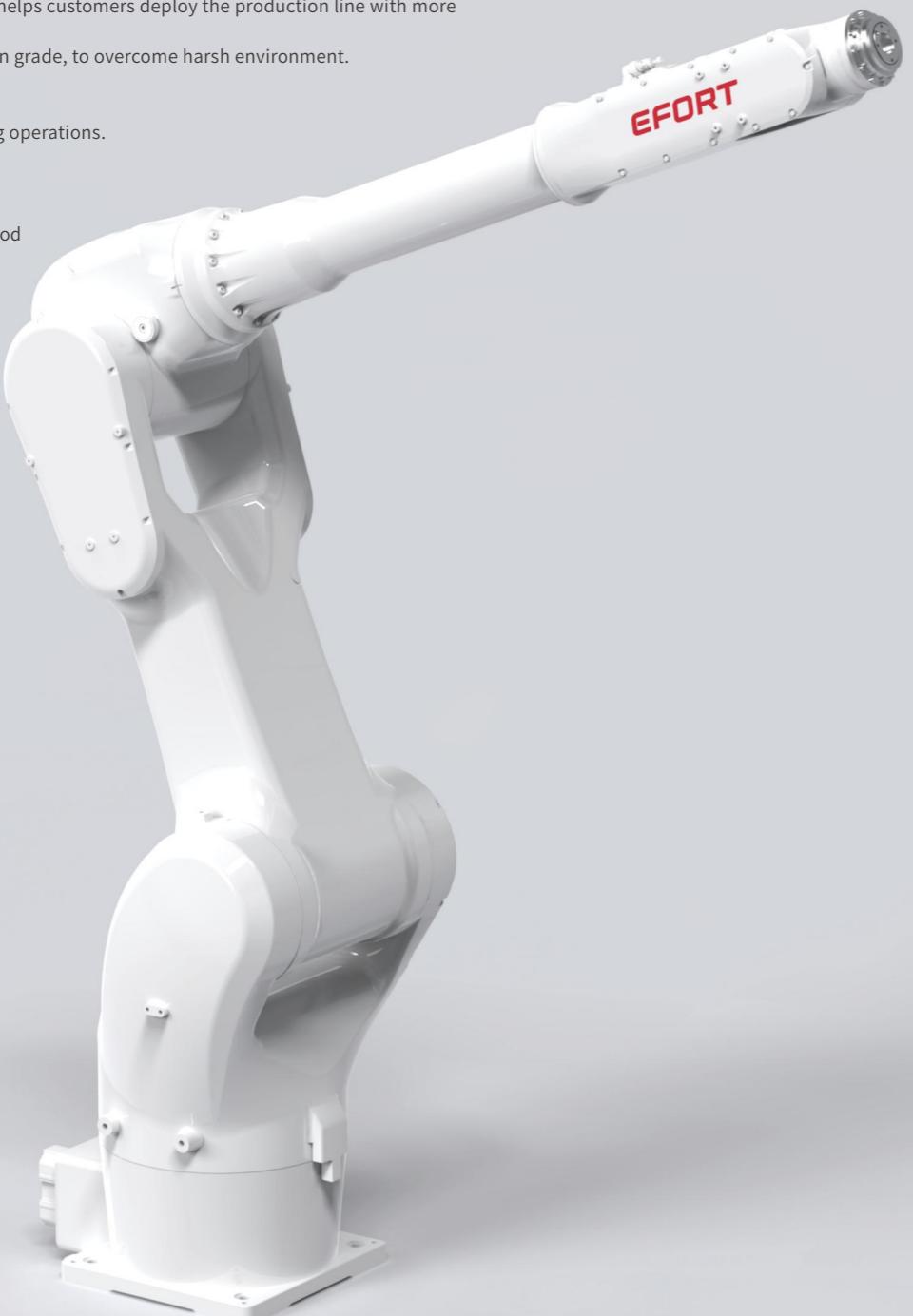
Thanks to the optimization of stiffness and inertia brought by the new mechanical design, with advanced trajectory algorithm. The takt improved by 20%-30%; Compact cabinet design helps customers deploy the production line with more flexibility; IP67 wrist, high protection grade, to overcome harsh environment.

Applications

It can be used in handling operations.

Industries

Suitable for metal parts, photovoltaic, logistics, food and beverage and other industries



EFORT Intelligent Robot Co., Ltd.
PHONE: (00 86) 400-052-8877
ADDRESS: No. 96, Wanchun East Road, Wuhu, China
(Anhui) Pilot Free Trade Zone
WWW.EFORT.COM.CN

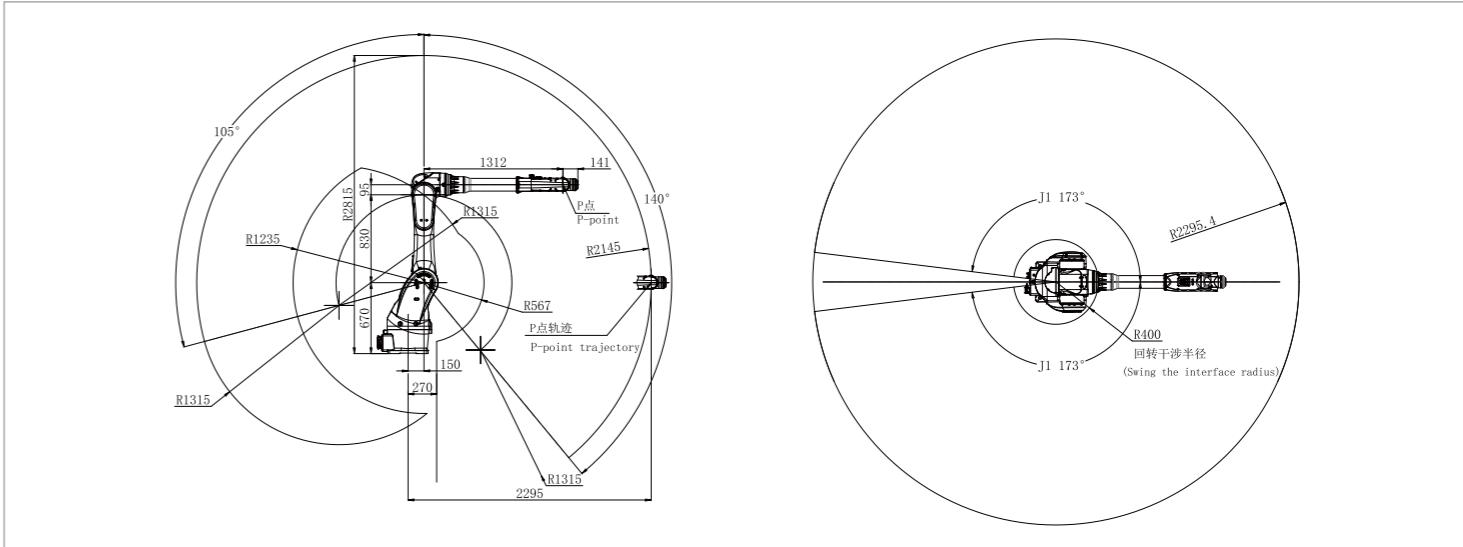
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SPECIFICATIONS

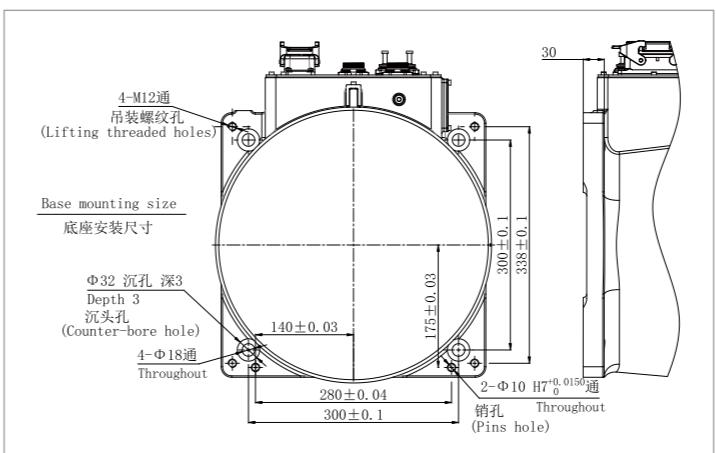
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|--------------------------------|--------------------------|-----------------------------------|
| Model | ER25-2300 | |
| Type | Articulated | |
| Controlled axes | 6 Axes | |
| Max. payload on wrist | 25 kg | |
| Repeatability | ±0.05 mm | |
| Robot weight | 315 kg | |
| Reach | 2295 mm | |
| Robot IP grade | IP54/IP67 (Wrist) | |
| Cabinet IP grade | IP20/IP54 (optional) | |
| Drive mode | AC servo drive | |
| Installation | Floor, Upside-down, Wall | |
| Installation enviroment | Ambient temperature | 0~45 °C |
| | Ambient humidity | RH≤80% (No dew nor frost allowed) |
| | Vibration acceleration | 4.9 m/s ² (<0.5 G) |

| | |
|------------|-----------------------|
| J 4 | 50 N·m |
| J 5 | 50 N·m |
| J 6 | 30 N·m |
| J 4 | 2.2 kg·m ² |
| J 5 | 2.2 kg·m ² |
| J 6 | 1.5 kg·m ² |
| J 1 | 190°/sec |
| J 2 | 190°/sec |
| J 3 | 200°/sec |
| J 4 | 350°/sec |
| J 5 | 360°/sec |
| J 6 | 410°/sec |
| J 1 | ±173° |
| J 2 | +105°/-141° |
| J 3 | +200°/-78° |
| J 4 | ±190° |
| J 5 | ±130° |
| J 6 | ±360° |

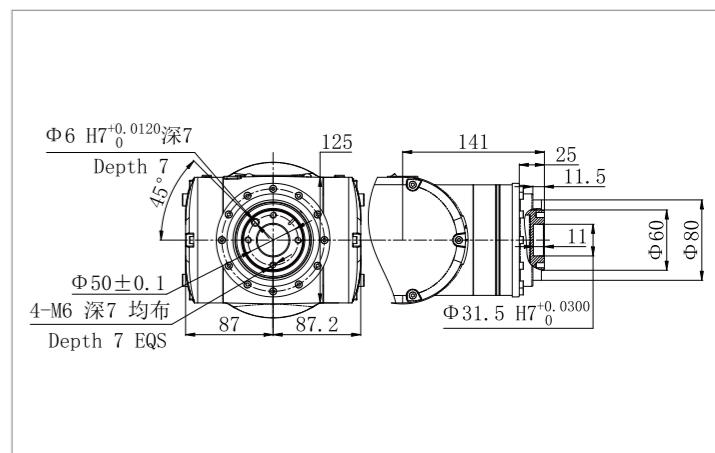
OPERATING SPACE



BASE MOUNTING SIZE



END FLANGE MOUNTING SIZE



*The final interpretation right belongs to EFORT Intelligent Robot Co., Ltd. Any updates will be made without prior notice.

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